

Nash equilibrium in quantitative games

Thomas BRIHAYE Véronique BRUYÈRE Julie DE PRIL

University of Mons (Belgium)

UMONS

2nd Meeting GASICS 2009
October 22, 2009

Outline

- 1 Context
- 2 Main results
- 3 Future work

Outline

- 1 Context
- 2 Main results
- 3 Future work

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- reachability objectives for all the players
- payoff: least number of edges to reach one's goal set, or $+\infty$
- aim: minimize one's payoff

↪ multiplayer, non-zero-sum, quantitative games

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- reachability objectives for all the players
- payoff: least number of edges to reach one's goal set, or $+\infty$
- aim: minimize one's payoff

↪ multiplayer, non-zero-sum, quantitative games

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- reachability objectives for all the players
- payoff: least number of edges to reach one's goal set, or $+\infty$
- aim: minimize one's payoff

↪ multiplayer, non-zero-sum, quantitative games

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- **reachability** objectives for all the players
- payoff: least number of edges to reach one's goal set, or $+\infty$
- aim: minimize one's payoff

↪ multiplayer, non-zero-sum, quantitative games

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- **reachability** objectives for all the players
- payoff: least **number of edges** to reach one's goal set, or $+\infty$
- aim: minimize one's payoff

↪ multiplayer, non-zero-sum, quantitative games

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- **reachability** objectives for all the players
- payoff: least **number of edges** to reach one's goal set, or $+\infty$
- aim: **minimize** one's payoff

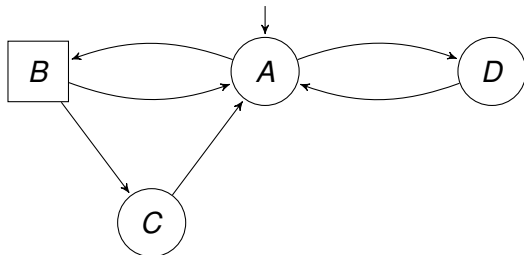
↪ multiplayer, non-zero-sum, quantitative games

Features of our games

- games on **finite graph** with no deadlock
- n players
- turn based
- **reachability** objectives for all the players
- payoff: least **number of edges** to reach one's goal set, or $+\infty$
- aim: **minimize** one's payoff

↪ multiplayer, non-zero-sum, quantitative games

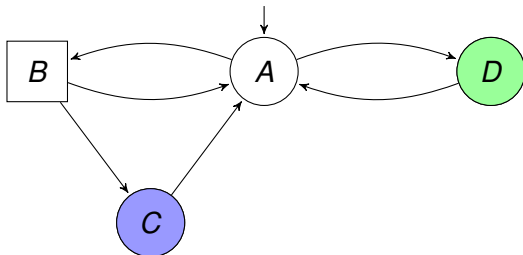
Example



Player 1 ○ $Reach_1 = \{C\}$

Player 2 □ $Reach_2 = \{D\}$

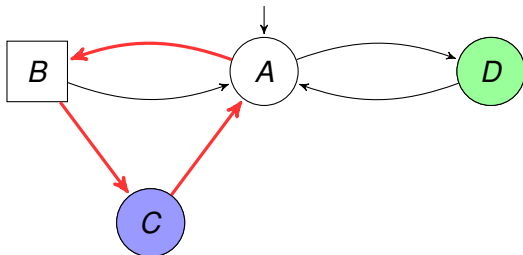
Example



Player 1 ○ $Reach_1 = \{C\}$

Player 2 □ $Reach_2 = \{D\}$

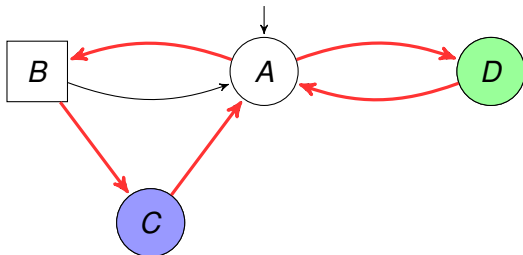
Example



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

Play: $(ABC)^\omega$
Payoffs: $(2, +\infty)$

Example

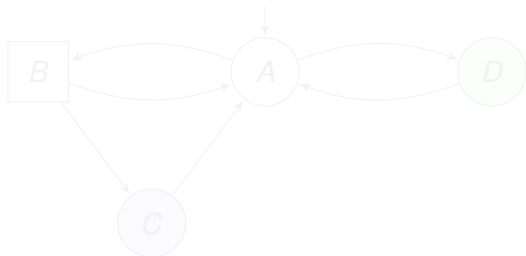


Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

Play: $AD(ABC)^\omega$
Payoffs: (4, 1)

Nash equilibrium in such games

Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.

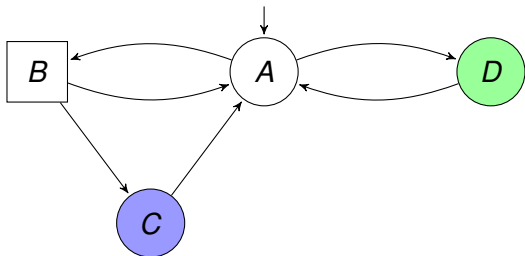


Player 1 ○ $Reach_1 = \{C\}$

Player 2 □ $Reach_2 = \{D\}$

Nash equilibrium in such games

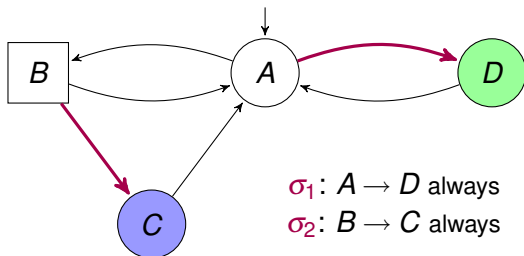
Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

Nash equilibrium in such games

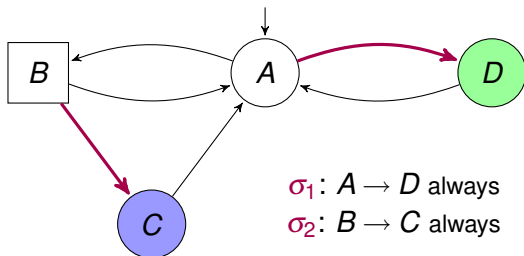
Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

Nash equilibrium in such games

Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.



Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$

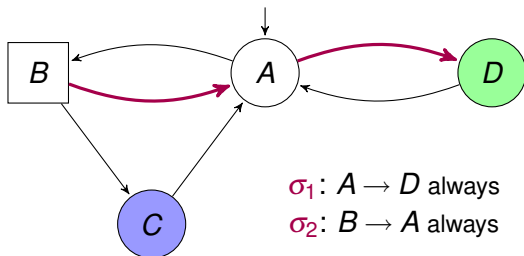
Play: $(AD)^\omega$

Payoffs: $(+\infty, 1)$

(σ_1, σ_2) : NOT a Nash equilibrium

Nash equilibrium in such games

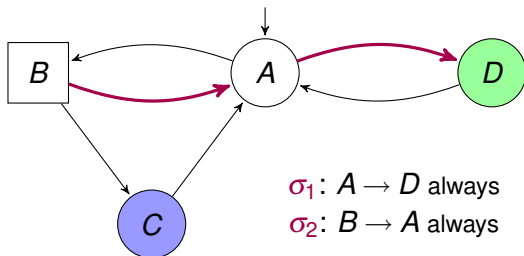
Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

Nash equilibrium in such games

Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.

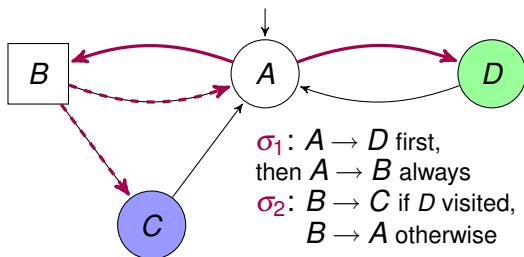


Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$

Play: $(AD)^\omega$
Payoffs: $(+\infty, 1)$
 (σ_1, σ_2) : Nash equilibrium

Nash equilibrium in such games

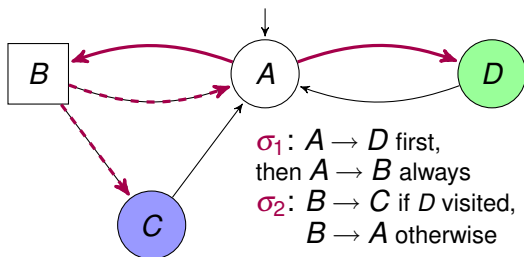
Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.



Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$

Nash equilibrium in such games

Idea: A strategy profile where no player has an incentive to deviate from the strategy chosen, given the choices of the other players.



Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$

Play: $AD(ABC)^\omega$

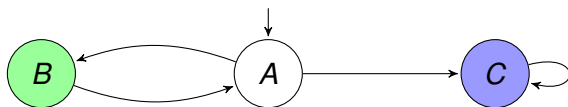
Payoffs: (4, 1)

(σ_1, σ_2) : Nash equilibrium

Qualitative NE \neq Quantitative NE

Player 1 \circ $Reach_1 = \{C\}$

Player 2 \square $Reach_2 = \{B\}$



$\sigma_1: A \rightarrow B$ first, then $A \rightarrow C$

Play: $ABAC^\omega$

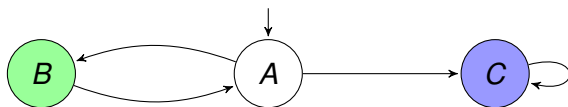
Qualitative payoff profile: (Win, Win) \rightsquigarrow qualitative Nash equilibrium

Quantitative payoff profile: (3, 1) but not a quantitative Nash equilibrium

Qualitative NE \neq Quantitative NE

Player 1 \circ $Reach_1 = \{C\}$

Player 2 \square $Reach_2 = \{B\}$



$\sigma_1: A \rightarrow B$ first, then $A \rightarrow C$

Play: $ABAC^\omega$

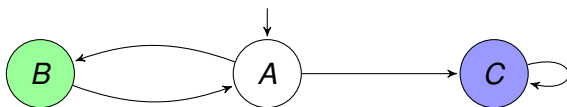
Qualitative payoff profile: (Win, Win) \rightsquigarrow qualitative Nash equilibrium

Quantitative payoff profile: (3, 1) but not a quantitative Nash equilibrium

Qualitative NE \neq Quantitative NE

Player 1 \circ $Reach_1 = \{C\}$

Player 2 \square $Reach_2 = \{B\}$



$\sigma_1: A \rightarrow B$ first, then $A \rightarrow C$

Play: $ABAC^\omega$

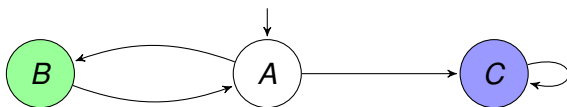
Qualitative payoff profile: (Win, Win) \rightsquigarrow qualitative Nash equilibrium

Quantitative payoff profile: (3, 1) but not a quantitative Nash equilibrium

Qualitative NE \neq Quantitative NE

Player 1 \circ $Reach_1 = \{C\}$

Player 2 \square $Reach_2 = \{B\}$



$\sigma_1: A \rightarrow B$ first, then $A \rightarrow C$

Play: $ABAC^\omega$

Qualitative payoff profile: (Win, Win) \rightsquigarrow qualitative Nash equilibrium

Quantitative payoff profile: (3, 1) but not a quantitative Nash equilibrium

Overview

	Zero-sum	Non-zero-sum
Qualitative	[Tho08],...	[CHJ06], [GU09],...
Quantitative	[HTW08], [BCHJ09],...	[BG09],...

- [BG09] Why chess and back gammon can be solved in pure positional uniformly optimal strategies
- [Tho08] Church's problem and a tour through automata theory
- [HTW08] Optimal strategy synthesis in request response games
- [BCHJ09] Better quality in synthesis through quantitative objectives
- [CHJ06] Games with secure equilibria
- [GU09] Solution concepts and algorithms for infinite multiplayer games

Motivation: e.g., solving games where everyone wants to minimize the time (or the energy consumption) to reach a given state set.

Overview

	Zero-sum	Non-zero-sum
Qualitative	[Tho08],...	[CHJ06], [GU09],...
Quantitative	[HTW08], [BCHJ09],...	[BG09],...

- [BG09] Why chess and back gammon can be solved in pure positional uniformly optimal strategies
- [Tho08] Church's problem and a tour through automata theory
- [HTW08] Optimal strategy synthesis in request response games
- [BCHJ09] Better quality in synthesis through quantitative objectives
- [CHJ06] Games with secure equilibria
- [GU09] Solution concepts and algorithms for infinite multiplayer games

Motivation: e.g., solving games where everyone wants to minimize the time (or the energy consumption) to reach a given state set.

Overview

	Zero-sum	Non-zero-sum
Qualitative	[Tho08],...	[CHJ06], [GU09],...
Quantitative	[HTW08], [BCHJ09],...	[BG09],...

- [BG09] Why chess and back gammon can be solved in pure positional uniformly optimal strategies
- [Tho08] Church's problem and a tour through automata theory
- [HTW08] Optimal strategy synthesis in request response games
- [BCHJ09] Better quality in synthesis through quantitative objectives
- [CHJ06] Games with secure equilibria
- [GU09] Solution concepts and algorithms for infinite multiplayer games

Motivation: e.g., solving games where everyone wants to minimize the time (or the energy consumption) to reach a given state set.

Outline

1 Context

2 Main results

- Existence of a Nash equilibrium
- Nash equilibrium with bounded memory
- Existence of a secure equilibrium

3 Future work

Existence of a Nash equilibrium

Theorem

There exists a Nash equilibrium in every multiplayer quantitative game with reachability objectives for all the players.

Player 1 ○ $Reach_1 = \{C\}$

Player 2 □ $Reach_2 = \{B\}$



No Nash equilibrium where both players reach their goal set. . .

But σ_1 leads to a Nash equilibrium, with payoff profile $(1, +\infty)$!

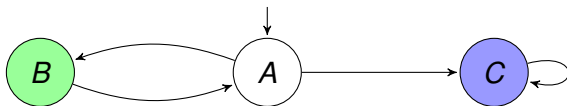
Existence of a Nash equilibrium

Theorem

There exists a Nash equilibrium in every multiplayer quantitative game with reachability objectives for all the players.

Player 1 ○ $Reach_1 = \{C\}$

Player 2 □ $Reach_2 = \{B\}$



No Nash equilibrium where both players reach their goal set...

But σ_1 leads to a Nash equilibrium, with payoff profile $(1, +\infty)$!

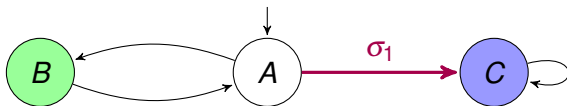
Existence of a Nash equilibrium

Theorem

There exists a Nash equilibrium in every multiplayer quantitative game with reachability objectives for all the players.

Player 1 ○ $Reach_1 = \{C\}$

Player 2 □ $Reach_2 = \{B\}$



No Nash equilibrium where both players reach their goal set. . .

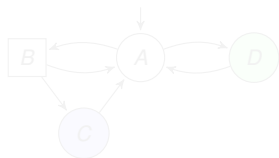
But σ_1 leads to a **Nash equilibrium**, with payoff profile $(1, +\infty)$!

Idea of the proof (1/4)

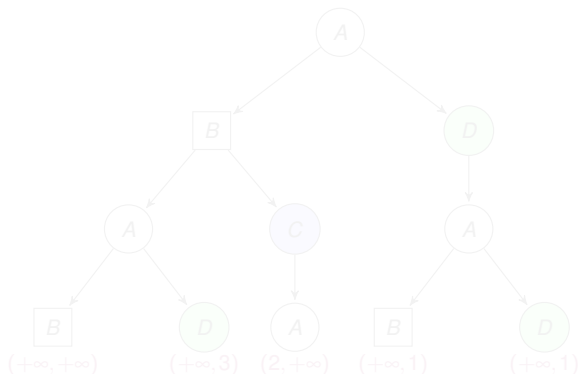
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$



Backward induction

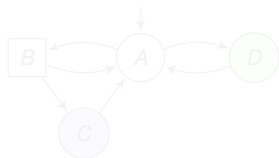


Idea of the proof (1/4)

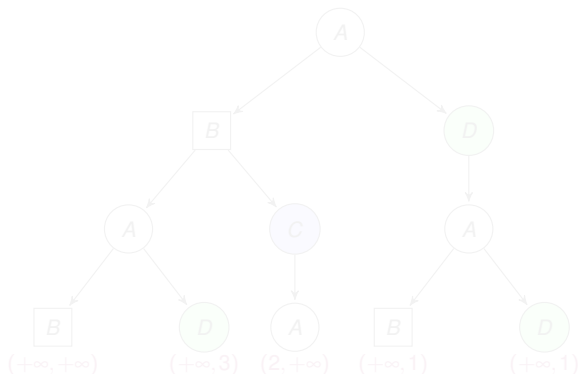
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$



Backward induction

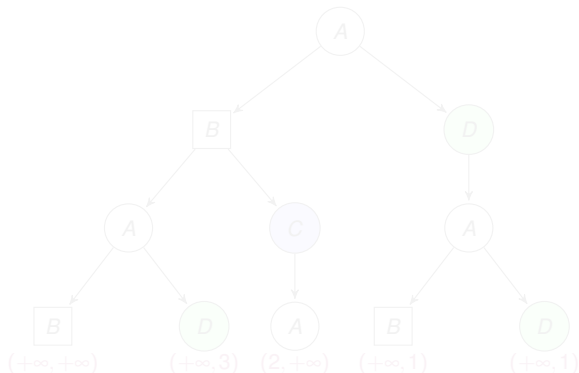
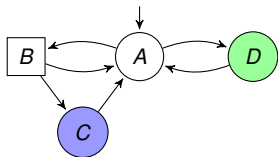


Idea of the proof (1/4)

Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$



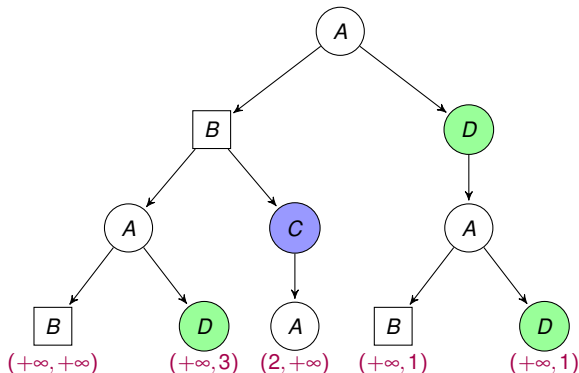
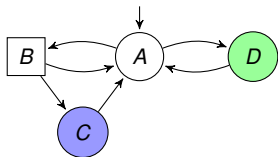
Backward induction

Idea of the proof (1/4)

Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$



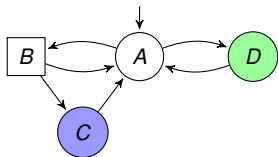
Backward induction

Idea of the proof (1/4)

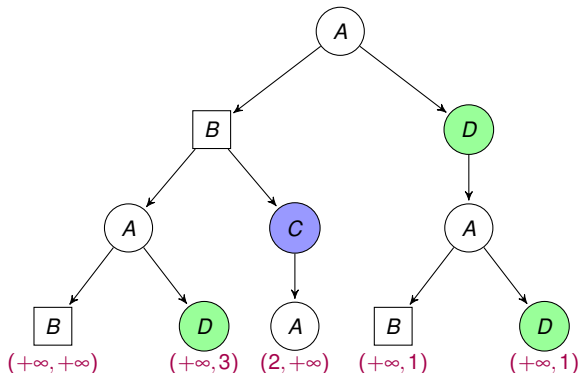
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$



Backward induction

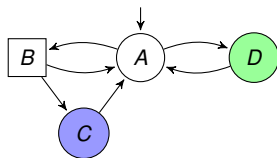


Idea of the proof (1/4)

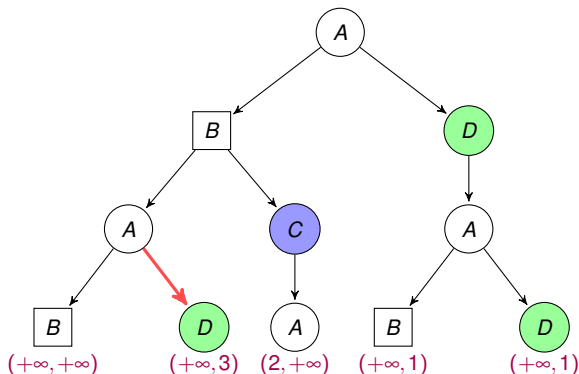
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$



Backward induction

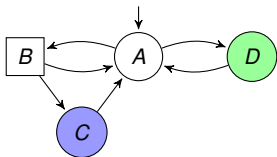


Idea of the proof (1/4)

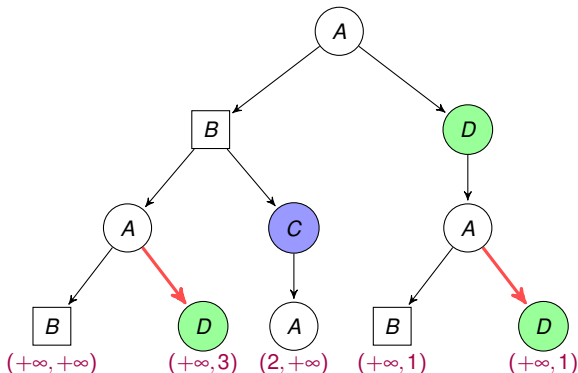
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$



Backward induction

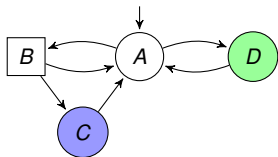


Idea of the proof (1/4)

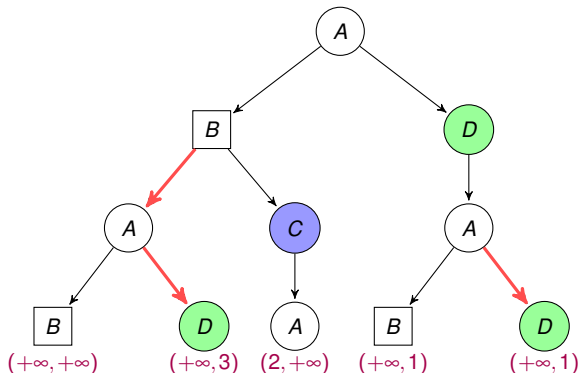
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$



Backward induction

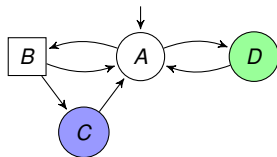


Idea of the proof (1/4)

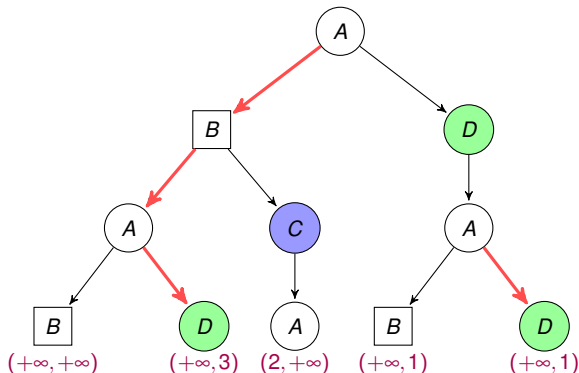
Consider the arena of an initialized game like an infinite tree.

Assume that the tree is finite. Then Kuhn's theorem provides a quantitative Nash equilibrium.

Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$



Backward induction



Idea of the proof (2/4)

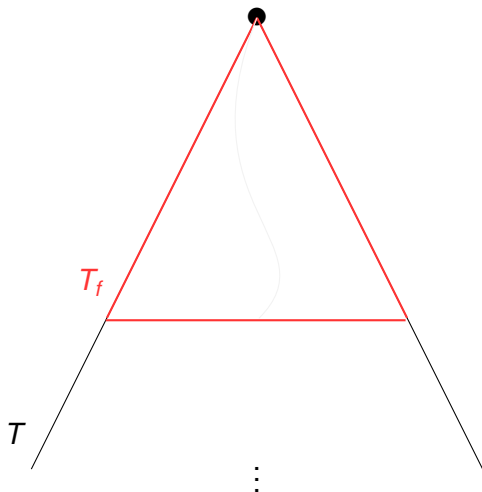
Thanks to Kuhn's theorem, if we prove the following result, we are done.

Proposition

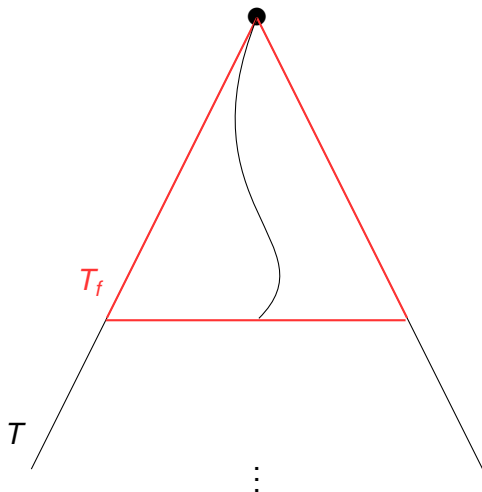
*Let T be the unravelling of the game and T_f be this tree limited to the depth $(n + 1) * 2 * |V|$.*

If there exists a Nash equilibrium in T_f , then there exists a Nash equilibrium in T .

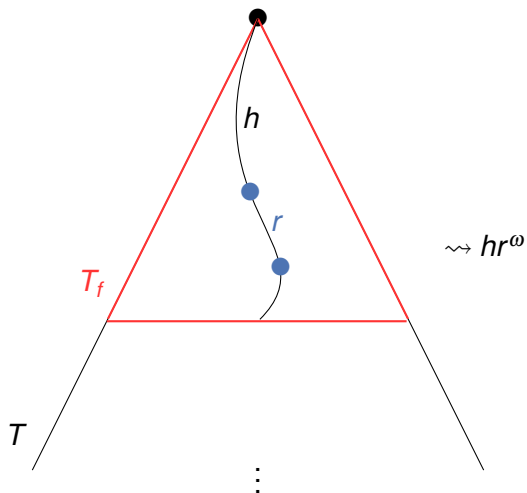
Idea of the proof (3/4)



Idea of the proof (3/4)



Idea of the proof (3/4)



Idea of the proof (4/4)

Nash equilibrium in T :

→ everyone plays according to hr^ω

→ as soon as one player deviates, the other ones **punish** him by playing a strategy that prevents him from reaching his goal set (more quickly).

Remark: payoff profile not preserved. . .

But no hope to do better (example)!

Idea of the proof (4/4)

Nash equilibrium in T :

→ everyone plays according to hr^ω

→ as soon as one player deviates, the other ones **punish** him by playing a strategy that prevents him from reaching his goal set (more quickly).

Remark: payoff profile not preserved. . .

But no hope to do better (example)!

Nash equilibrium with bounded memory

Theorem

There exists a NE of payoff profile $(c_i)_i$ iff there exists a NE of payoff profile $(c_i)_i$ where the strategies have bounded memory.

Idea of the proof:

- transform the play of the NE into a play of the form hr^ω (keeping the same payoff profile) ;
- the Nash equilibrium with bounded memory will be:
 - everyone plays according to hr^ω
 - as soon as one player deviates, the other ones punish him by playing a bounded memory strategy that prevents him from reaching his goal set (more quickly).

Nash equilibrium with bounded memory

Theorem

There exists a NE of payoff profile $(c_i)_i$ iff there exists a NE of payoff profile $(c_i)_i$ where the strategies have bounded memory.

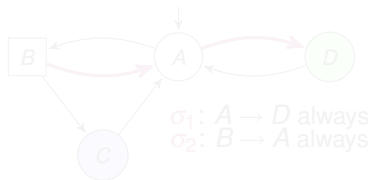
Idea of the proof:

- transform the play of the NE into a play of the form hr^ω (keeping the same payoff profile) ;
- the Nash equilibrium with bounded memory will be:
 - everyone plays according to hr^ω
 - as soon as one player deviates, the other ones **punish** him by playing a bounded memory strategy that prevents him from reaching his goal set (more quickly).

Secure equilibrium in such games

Idea: A strategy profile

- that is a Nash equilibrium; and
- such that if a player gets the same payoff when deviating, he can not increase the other players' payoffs and increase strictly one player's payoff.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

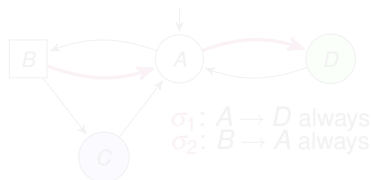
Play: $(AD)^\omega$
Payoffs: $(+\infty, 1)$

(σ_1, σ_2) : Nash equilibrium
 (σ_1, σ_2) : NOT a secure equilibrium

Secure equilibrium in such games

Idea: A strategy profile

- that is a Nash equilibrium; and
- such that if a player gets the same payoff when deviating, he can not increase the other players' payoffs and increase strictly one player's payoff.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

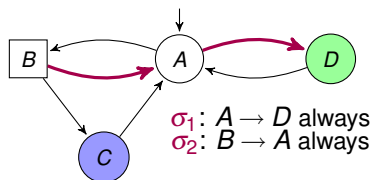
Play: $(AD)^\omega$
Payoffs: $(+\infty, 1)$

(σ_1, σ_2) : Nash equilibrium
 (σ_1, σ_2) : NOT a secure equilibrium

Secure equilibrium in such games

Idea: A strategy profile

- that is a Nash equilibrium; and
- such that if a player gets the same payoff when deviating, he can not increase the other players' payoffs and increase strictly one player's payoff.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

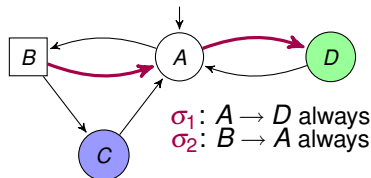
Play: $(AD)^\omega$
Payoffs: $(+\infty, 1)$

(σ_1, σ_2) : Nash equilibrium
 (σ_1, σ_2) : NOT a secure equilibrium

Secure equilibrium in such games

Idea: A strategy profile

- that is a Nash equilibrium; and
- such that if a player gets the same payoff when deviating, he can not increase the other players' payoffs and increase strictly one player's payoff.



Player 1 \circ $Reach_1 = \{C\}$
Player 2 \square $Reach_2 = \{D\}$

Play: $(AD)^\omega$
Payoffs: $(+\infty, 1)$

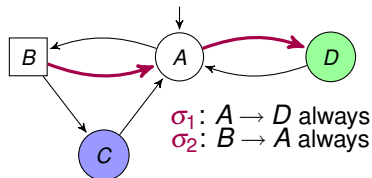
(σ_1, σ_2) : Nash equilibrium

(σ_1, σ_2) : NOT a secure equilibrium

Secure equilibrium in such games

Idea: A strategy profile

- that is a Nash equilibrium; and
- such that if a player gets the same payoff when deviating, he can not increase the other players' payoffs and increase strictly one player's payoff.



Player 1 ○ $Reach_1 = \{C\}$
Player 2 □ $Reach_2 = \{D\}$

Play: $(AD)^\omega$
Payoffs: $(+\infty, 1)$

(σ_1, σ_2) : Nash equilibrium
 (σ_1, σ_2) : NOT a secure equilibrium

Existence of a secure equilibrium

Theorem

There exists a secure equilibrium in every multiplayer quantitative game with reachability objectives for all the players.

Proof: Same ideas as for the existence of a Nash equilibrium.

Existence of a secure equilibrium

Theorem

There exists a secure equilibrium in every multiplayer quantitative game with reachability objectives for all the players.

Proof: Same ideas as for the existence of a Nash equilibrium.

Outline

- 1 Context
- 2 Main results
- 3 Future work

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
 - Subgame perfect equilibrium
 - Büchi objectives
 - Request-response games
 - Memory size
 - Mixed strategies
 - ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Future work

- Positive costs on edges: OK
(payoff = sum of costs to reach one's goal set)
- Complexity
- Subgame perfect equilibrium
- Büchi objectives
- Request-response games
- Memory size
- Mixed strategies
- ...

Thank you for your attention!